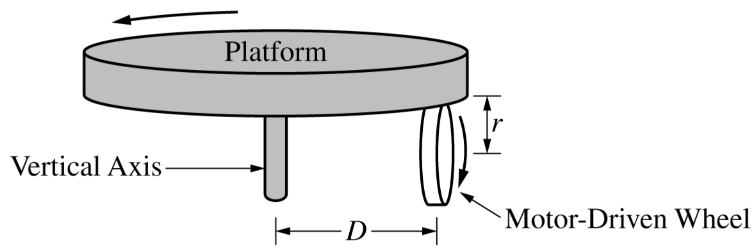
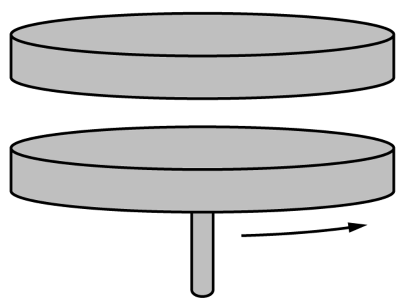


3. A horizontal circular platform with rotational inertia I_P rotates freely without friction on a vertical axis. A small motor-driven wheel that is used to rotate the platform is mounted under the platform and touches it. The wheel has radius r and touches the platform a distance D from the vertical axis of the platform, as shown above. The platform starts at rest, and the wheel exerts a constant horizontal force of magnitude F tangent to the wheel until the platform reaches an angular speed ω_P after time Δt. During time Δt, the wheel stays in contact with the platform without slipping.

   (a) Derive an expression for the angular speed ω_P of the platform. Express your answer in terms of I_P, r, D, F, Δt, and physical constants, as appropriate.

   (b) Determine an expression for the kinetic energy of the platform at the moment it reaches angular speed ω_P. Express your answer in terms of I_P, r, D, F, Δt, and physical constants, as appropriate.

   (c) Derive an expression for the angular speed of the wheel ω_W when the platform has reached angular speed ω_P. Express your answer in terms of D, r, ω_P, and physical constants, as appropriate.

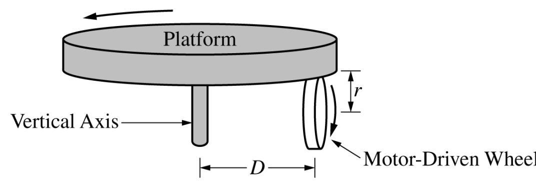


   When the platform is spinning at angular speed ω_P, the motor-driven wheel is removed. A student holds a disk directly above and concentric with the platform, as shown above. The disk has the same rotational inertia I_P as the platform. The student releases the disk from rest, and the disk falls onto the platform. After a short time, the disk and platform are observed to be rotating together at angular speed ω_f.

   (d) Derive an expression for ω_f. Express your answer in terms of ω_P, I_P, and physical constants, as appropriate.

Question 3

15 points



A horizontal circular platform with rotational inertia I_P rotates freely without friction on a vertical axis. A small motor-driven wheel that is used to rotate the platform is mounted under the platform and touches it. The wheel has radius r and touches the platform a distance D from the vertical axis of the platform, as shown above. The platform starts at rest, and the wheel exerts a constant horizontal force of magnitude F tangent to the wheel until the platform reaches an angular speed ω_P after time Δt . During time Δt , the wheel stays in contact with the platform without slipping.

(a) LO INT-7.A.b, CHA-4.A.b, SP 5.A, 5.E
2 points

Derive an expression for the angular speed ω_P of the platform. Express your answer in terms of I_P, r, D, F, Δt , and physical constants, as appropriate.

For correctly substituting into the rotational form of Newton's second law			1 point
$\tau = I\alpha \therefore FD = I_P\alpha$			
$\alpha = \dfrac{FD}{I_P}$			
For correctly substituting into a rotational kinematic equation to calculate the angular speed			1 point
$\omega_2 = \omega_1 + \alpha\Delta t = 0 + \left(\dfrac{FD}{I_P}\right)\Delta t$			
$\omega_P = \dfrac{FD\Delta t}{I_P}$			

(b) LO INT-7.D.a, SP 5.A, 5.E
2 points

Determine an expression for the kinetic energy of the platform at the moment it reaches angular speed ω_P. Express your answer in terms of I_P, r, D, F, Δt , and physical constants, as appropriate.

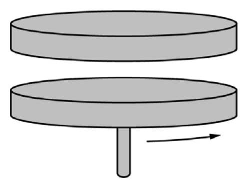
For using the equation for rotational kinetic energy		1 point
$K = \dfrac{1}{2}I\omega_P^2 = \left(\dfrac{1}{2}\right)(I)\left(\dfrac{FD\Delta t}{I}\right)^2$		
For an answer consistent with part (a)		1 point
$K = \dfrac{(FD\Delta t)^2}{2I}$		

Question 3 (continued)

(c) LO INT-7.C, SP 5.A, 5.E
2 points

Derive an expression for the angular speed of the wheel ω_W when the platform has reached angular speed ω_P. Express your answer in terms of D, r, ω_P, and physical constants, as appropriate.

For indicating that the linear speed of the platform is equal to the linear speed of the wheel		1 point
$v_P = v_W$ OR $(r\omega)_P = (r\omega)_W$		
For correctly relating the linear speeds to the angular speeds in the above equation		1 point
$D\omega_P = r\omega_W$		
$\omega_W = \dfrac{D\omega_P}{r}$		



When the platform is spinning at angular speed ω_P, the motor-driven wheel is removed. A student holds a disk directly above and concentric with the platform, as shown above. The disk has the same rotational inertia I_P as the platform. The student releases the disk from rest, and the disk falls onto the platform. After a short time, the disk and platform are observed to be rotating together at angular speed ω_f.

(d) LO CON-5.D.c, SP 5.A, 5.E
2 points

Derive an expression for ω_f. Express your answer in terms of ω_P, I_P, and physical constants, as appropriate.

For using an expression for the conservation of angular momentum		1 point
$L_1 = L_2 \therefore I_1\omega_1 = I_2\omega_2$		
For correctly substituting into the above equation		1 point
$I\omega_P = (2I)\omega_F$		
$\omega_F = \dfrac{1}{2}\omega_P$		

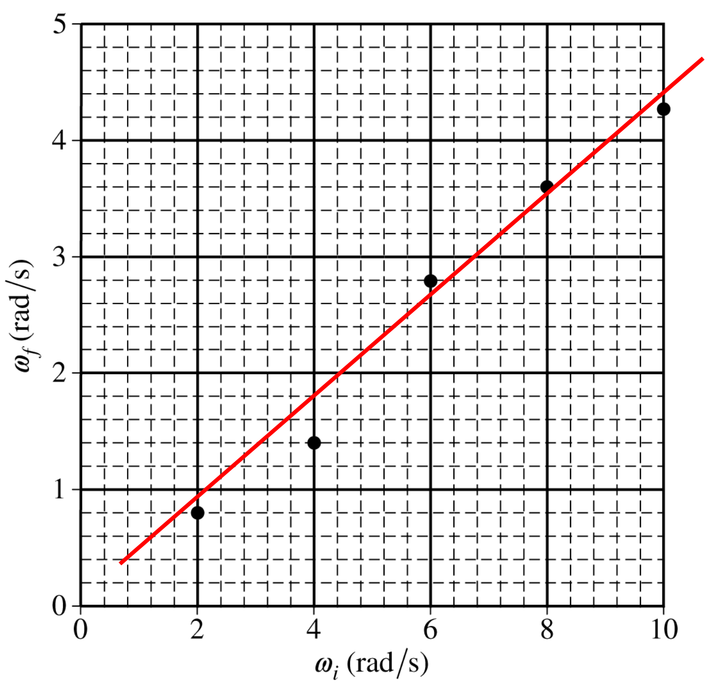
Question 3 (continued)

A student now uses the rotating platform $\left(I_P = 3.1 \text{ kg} \bullet \text{m}^2\right)$ to determine the rotational inertia I_U of an unknown object about a vertical axis that passes through the object's center of mass. The platform is rotating at an initial angular speed ω_i when the unknown object is dropped with its center of mass directly above the center of the platform. The platform and object are observed to be rotating together at angular speed ω_f . Trials are repeated for different values of ω_i . A graph of ω_f as a function of ω_i is shown on the axes below.

(e)

i. LO CON-5.D.c, SP 4.C
1 points

On the graph on the previous page, draw a best-fit line for the data.



For an appropriate best-fit line for the graph above		1 point

Question 3 (continued)

(e) continued

ii. LO CON-5.D.c, SP 4.D, 6.C
2 points

Using the straight line, calculate the rotational inertia of the unknown object I_U about a vertical axis passing through its center of mass.

For using conservation of angular momentum to derive an expression that includes I_U		1 point
$L_i = L_f \therefore I_P\omega_i = (I_P + I_U)\omega_f$		
$I_U = I_P\left(\dfrac{\omega_i}{\omega_f}\right) - I_P$		
For substituting points from the best-fit line into the expression above		1 point
$I_U = (3.1\ \text{kg}\bullet\text{m}^2)\left(\dfrac{(4.0 - 1.0)\ \text{rad/s}}{(9.3 - 2.4)\ \text{rad/s}}\right) - (3.1\ \text{kg}\bullet\text{m}^2) = 4.1\ \text{kg}\bullet\text{m}^2$		
<u>Note:</u> The point (0, 0) can be used implicitly if the best-fit line goes through the origin.		

(f) LO CON-5.D.c, SP 7.A, 7.C
2 points

The kinetic energy of the spinning platform before the object is dropped on it is K_i. The total kinetic energy of the platform-object system when it reaches angular speed ω_f is K_f. Which of the following expressions is true?

____ $K_f < K_i$ ____ $K_f = K_i$ ____ $K_f > K_i$

Justify your answer.

For selecting $K_f < K_i$ with an attempt at a relevant justification		1 point
For a correct justification		1 point
Example: Because the two disks will be rotating with the same final angular speed, this is an inelastic collision, and kinetic energy will be lost during the collision.		

Question 3 (continued)

(g) LO INT-6.E, SP 7.A, 7.C
2 points

One of the students observes that the center of mass of the object is not actually aligned with the axis of the platform. Is the experimental value of I_U obtained in part (e) greater than, less than, or equal to the actual value of the rotational inertia of the unknown object about a vertical axis that passes through its center of mass?

____ Greater than ____ Less than ____ Equal to

Justify your answer.

For selecting "Greater than" with an attempt at a relevant justification		1 point
For a correct justification		1 point
Example: Because the center of mass of the object is off the axis of the platform, the parallel axis theorem would be used to calculate the total rotational inertia of the platform-object system. Using $I = I_{CM} + Mh^2$, the experimental value will be increased by Mh^2.		

Learning Objectives

INT-6.E: Derive the moments of inertia of an extended rigid body for different rotational axes (parallel to an axis that goes through the object's center of mass) if the moment of inertia is known about an axis through the object's center of mass.
CHA-4.A.b: Calculate unknown quantities such as angular positions, displacement, angular speeds, or angular acceleration of a rigid body in uniformly accelerated motion, given initial conditions.
INT-7.A.b: Calculate unknown quantities such as net torque, angular acceleration, or moment of inertia for a rigid body undergoing rotational acceleration.
INT-7.C: Derive expressions for physical systems such as Atwood Machines, pulleys with rotational inertia, or strings connecting discs or strings connecting multiple pulleys that relate linear or translational motion characteristics to the angular motion characteristics of rigid bodies in the system that are: **(a)** rolling (or rotating on a fixed axis) without slipping. **(b)** rotating and sliding simultaneously.
INT-7.D.a: Calculate the rotational kinetic energy of a rotating rigid body.
CON-5.D.c: Calculate the changes of angular momentum of each disc in a rotating system of two rotating discs that collide with each other inelastically about a common rotational axis.

Science Practices

4.C: Linearize data and/or determine a best-fit line or curve.
4.D: Select relevant features of a graph to describe a physical situation or solve problems.
5.A: Select an appropriate law, definition, or mathematical relationship or model to describe a physical situation.
5.E: Derive a symbolic expression from known quantities by selecting and following a logical algebraic pathway.
6.C: Calculate an unknown quantity with units from known quantities, by selecting and following a logical computational pathway.
7.A: Make a scientific claim.
7.C: Support a claim with evidence from physical representations.